



# Distributed Information Processing

1<sup>st</sup> Lecture

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# Outline

- Introduction to Distributed Systems
- Clock
- Q&A

# Distributed Systems

■ Systems Where Components of Networked Computers Communicate and Coordinate Their Actions via Message Passing

□ Concurrency

□ No Global Clock

□ Independent Failures

- Sharing States
- Providing Services
- Having Global Properties
- Heterogeneity
- Unreliable, Insecure, Costly Comm.
- Scalability
- Autonomy

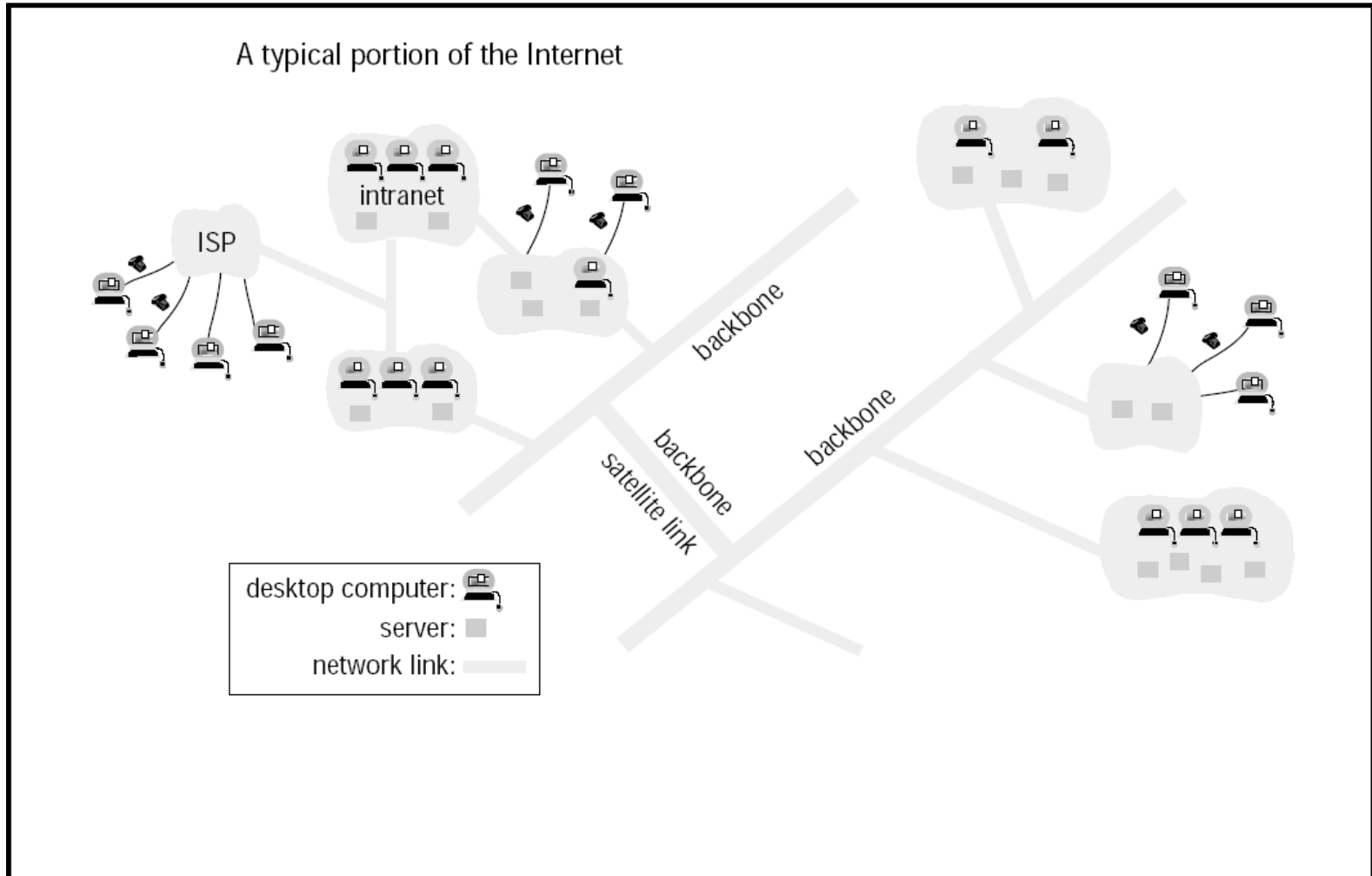
■ Systems Consisting of Collections of Spatially Separated Processes Communicating by Exchanging Messages

# Different-Scale Systems

- Systems of Increasing Scale & Decreasing Integration

System Type	Heterogeneity, Geographic Distribution	Lack of Centralized Control	Exemplar Computational Model
End (Single) System			Multithreading
Cluster			Distributed Shared Memory
Intranet	○		Manager/Worker
Internet	○	○	Collaborative Systems

# Example of Distributed Systems





# Distributed System Goals

## ■ Accessibility

- As Connectivity and Sharing Increases, Security and Privacy Matter

## ■ Distribution Transparency

- Access: Regarding Data Representation & Access Method
- Location: Regarding Resource Location
- Migration: Regarding Resource Movement
- Relocation: Regarding Movement in Use
- Replication: Regarding Resource Replication

# Distributed System Goals (Cont'd)

## ■ Distribution Transparency (Cont'd)

- Concurrency: Regarding Competitive Sharing
- Failure: Regarding Resource Failure and Recovery

### Performance & Comprehensibility Issues

## ■ Openness:

Following Standard Rules That Describe the Syntax and Semantics of Services

- Interoperability

# Distributed System Goals (Cont'd)

## ■ Openness (Cont'd)

- Portability
- Extensibility

Separating Policy from Mechanism

## ■ Scalability

- Limitations
  - Centralized services
  - Centralized data
  - Centralized algorithms
  - Synchronous communication



# Distributed System Goals (Cont'd)

## ■ Scalability (Cont'd)

### □ Decentralized Characteristics

- No local maintenance of global system state
- Decision making based only on local information
- Localized Failure
- No global clock

### □ Scaling Techniques

- Asynchronous communication
- Client and Server load balancing
- Distribution: e.g., DNS & WWW
- Replication & caching



# Distributed System Goals (Cont'd)


## ■ Pitfalls

- Network Reliability
- Network Security
- Network Homogeneity
- Static Topology
- Zero Latency
- Infinite Bandwidth
- Zero Transport Cost
- One Administrator



# Technical Goals

- Heterogeneity
  - H/W, S/W, and Data Components
- Varying Component Size and Extent
- Network Connection
- Uniform Set of Services
- Certain Global Properties



# Distributed Computing Approaches

- Grid
  - Addressing Infrastructure
- Peer-to-Peer
  - Addressing Failure
    - Self-organizing into network topologies
  - w/o a Global Server or Authority



# Distributed System Types

## ■ Distributed Computing Systems

### □ Cluster Computing Systems

- Collection of computers connected in a high-speed network

### □ Grid Computing Systems

- Federation of computer systems possibly in different administrative domains

## ■ Distributed Information Systems

### □ Transaction Processing Systems

- Atomic, Consistent, Isolated, and Durable Transaction

# Distributed System Types (Cont'd)

## ■ Distributed Information Systems (Cont'd)

### □ Enterprise Application Integration

#### ■ Communicating Independent Components

- Remote procedure call
- Remote method invocation
- Message-oriented middleware w/ logical contact points
  - Message queuing model
  - Message brokers as application-level gateway w/ subscription & publication

### □ Distributed Pervasive Systems

- Home Systems Possibly w/ UPnP
- Electronic Health Care Systems in a BAN
- Sensor Networks



# Issues

- Problem

- No Global Clock

- Issues

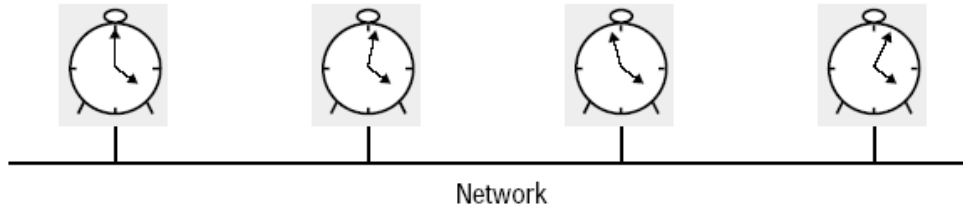
- How to Determine an Order of Events
  - How to Determine Global States
    - Consistency

# Clock

## ■ Skew

- Difference between the Readings of Any Two Clocks

Skew between computer clocks in a distributed system



Coulouris, Dollimore and Kindberg Distributed Systems: Concepts and Design Edn. 4 © Pearson Education 2005

## ■ Drift

- Divergence of Clocks due to Counting Times at Different Rates



# UTC (Coordinated Universal Time)

- International Time Standard
  - Formerly, Greenwich Mean Time or GMT
    - Zero hours UTC: midnight Greenwich (0 degrees longitude)
  - Based on Atomic Time (Drift Rate:  $1/10^{13}$  Seconds/Second)
    - Signals synchronized and broadcast regularly
      - From land-based radio stations and satellites

# Synchronous vs Asynchronous

## ■ Synchronous Systems

### □ Known Bounds

- Drift rate of clocks
- Max message transmission delay
- Time to execute each step of a process

## ■ Asynchronous Systems

### □ No Bounds